Track4 "Foot-Mounted IMU (offsite-online)" special features

Organizational aspects:

Database/dataset access

- As initiated last in Spain in 2021, Track4 is now an "offsite-online" track. That means, we ask to competitors to process data **as if they were in real time**. To do so, an interface based on a web API has been developed: EvaalAPI. This API will be used by competitors for sending position estimates and reading the sensor values:
  https://evaal.aaloa.org/evaalapi/
- In the context of this EvaalAPI framework, two "scoring trial" ("scoring trial#1" and "scoring trial#2" described later) will be proposed to competitors. **Each of these scoring trial will be usable only once**. Competitors have thus two trials, for the evaluation.
- In order to help competitors to be prepared for the evaluation, a "testing trial" is proposed. This "testing trial" is fully accessible or reloadable (ie not restricted to a single usage as scoring trials). GroundTruth positions are included in the "testing trial" under the POSI label, for validation purpose.
- Extract from https://evaal.aaloa.org/2023/call-for-competition :
  "OFFSITE-ONLINE TRACKS : *Competitors are provided with sensors data and use them to estimate the user position. Competitors calibrate their algorithms in advance using ground truth reference data (testing trials) and compete using new unreferenced data (scoring trials). Competitors run their Trials through the EvaalAPI in the usual online mode to emulate the causal, real-time behavior of onsite Tracks. Scoring trials are run on a Track-specific day during the second week of September.*"

Competitor admission process / Application:

- See: https://evaal.aaloa.org/2023/call-for-competition

Submission of the processed results

- As mentioned earlier, results have to be submitted via a web API. See above.
- A participant team can run the process up to 2 times. This lets a chance to catch-up if any issues happen. Although the competition organizers will evaluate the two scoring trials, only the best one will be considered for the contest. These two datasets correspond to two different data collection performed on the same path but not at the same time.

Important deadlines:

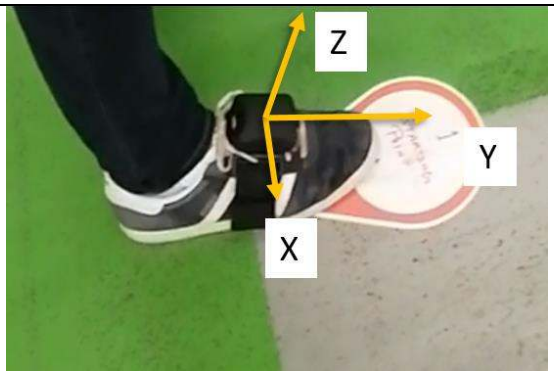
• Technical annexes published	**April, 2023**
• "testing trial" is accessible by files	**April, 2023**
• Application deadline	**May 31st, 2023**
• "testing trial" is accessible through web API	**June, 2023**
• **"scoring trial#1" and "scoring trial#2" will be accessible**	**TBD (in September)**
• Proclamation of winners	**September 28th, 2023**

Scope

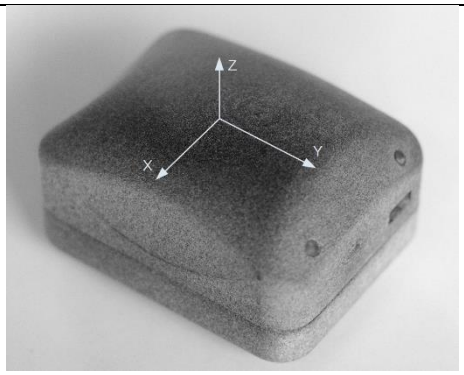
Many indoor navigation systems have been developed for pedestrians and assessing their performances is a real challenge. Benefiting from a reference solution that is accurate enough to evaluate other indoor navigation systems and assist novel research is of prime interest. According to ISO18305:2016 two different ways can be used for assessing indoor localization system: “Off-line surveyed test point” that is commonly used, or “reference system” with an accuracy at least one order of magnitude better the system you want to test. The scope of this track4 is clearly focused on the second way of assessing.
This track4 is based on the same equipment named “ULISS” as previous competitions hold during IPIN2022 and IPIN2021.

Competition Goal

The goal of this competition is to evaluate how good up-to-date INS algorithm is. Each competitor will have access to a dataset logged with ULISS (Ubiquitous Localization with Inertial Sensors and Satellites), a state-of-the-art Inertial Navigation System producing IMU data, MAG data, PRESSURE data & GNSS data, without the help of any maps.



ULISS sensor installed on the right foot (with axes), on the starting point.



ULISS sensors axes

Description of Datasets

Data is recorded from 3 different sensors:

Xsens Mti-7 	IMU-Mag sensor: -3D accelerometer -3D gyrometer -3D magnetometer https://www.xsens.com/mti-7
BMP280 sensor 	Operation range: Pressure: 300...1100 hPa Absolute accuracy : ~ ±1 hPa Relative accuracy : ± 0.12 hPa (typical) https://www.bosch-sensortec.com/products/environmental-sensors/pressure-sensors/bmp280/
Ublox ZED-F9P dual freq. receiver	Multi GNSS Receiver : BeiDou, Galileo, GLONASS, GPS / QZSS Number of concurrent GNSS 4

	Dual GNSS Bands : L1C/A, L2C, L1OF, L2OF, E1B/C, E5b, B1I, B2I https://www.u-blox.com/en/product/zed-f9p-module

Unit and meaning of the sensors outputs of ULISS are the following ones:

Column	Xsens MTi-1 (accelerometer)	Comments
1	Acceleration label	"ACCE"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Acc X (m/s²)	
4	Acc Y (m/s²)	
5	Acc Z (m/s²)	

Sample strings for accelerometer data

```
ACCE,314410.003952000,-1.25709,-4.34142,8.75831
ACCE,314410.008947000,-1.23771,-4.28408,8.72497
ACCE,314410.013942000,-1.26714,-4.3795,8.72491
ACCE,314410.018937000,-1.26167,-4.29823,8.71566
ACCE,314410.023932000,-1.25662,-4.26479,8.71095
```

Column	Xsens MTi-1 (gyrometer)	Comments
1	Gyrometer label	"ROTA"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Gyro X (rad/s)	
4	Gyro Y (rad/s)	
5	Gyro Z (rad/s)	

Sample strings for gyrometer data

```
ROTA,314410.004573000,0.00275338,-0.000805736,0.006387
ROTA,314410.009578000,-0.00576329,-0.00401807,0.00535798
ROTA,314410.014582000,0.00813067,0.00989926,0.00747764
ROTA,314410.019587000,0.00594413,-0.00079453,0.00529695
ROTA,314410.024591000,0.00488472,0.00237882,0.0117271
```

Column	Xsens MTi-1 (magnetometer)	Comments
1	Magnetometer label	"MAGN"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Mag X (a.u.)	a.u. = arbitrary unit according to Xsens.
4	Mag Y (a.u.)	Tips : multiply by 0.49*1000,
5	Mag Z (a.u.)	In order to get milliGauss (mG)

Sample strings for magnetometer data

```
MAGN,314410.005162000,0.224368,0.435266,-1.14962
MAGN,314410.015162000,0.22387,0.434764,-1.14766
MAGN,314410.025162000,0.222876,0.438141,-1.1481
MAGN,314410.035162000,0.223393,0.433828,-1.14817
MAGN,314410.045162000,0.224333,0.431291,-1.1413
```

Column	BMP280 (pressure)	Comments
1	Pressure sensor label	"PRES"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Pressure (Pa)	

Sample strings for pressure data

```
PRES,314410.005162000,101144
PRES,314410.025162000,101152
PRES,314410.045162000,101138
PRES,314410.065162000,101151
PRES,314410.085162000,101151
```

Column	Temperature (temperarure)	Comments
1	Temperature sensor label	"TEMP"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Temperature (Degree Celsius)	

Sample strings for temperature data

```
TEMP,314410.025162000,44.1914
TEMP,314411.025162000,44.1758
TEMP,314412.025162000,44.1758
```

Column	Ublox F9P GNSS receiver (SBS)	Comments
1	GNSS SBAS information label	"GSBS"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Hexadecimal WORD	Corresponds to EGNOS SBAS Message Format*

*: https://gssc.esa.int/navipedia/index.php/The_EGNOS_SBAS_Message_Format_Explained

Sample strings for SBS (SBAS – EGNOS) data

```
GSBS,315499,9A494C0000000000000400001F00003F80003FC0003FE0001FF0001FF80
GSBS,315618,5363FBFFDC00000000000197BBBAA01848160A0580B185BFDFEF980900
GSBS,315619,9A0A8003FE4027FFBFC7FEFFD4003FEC000003FB8003959559797BA380
```

Column	Ublox F9P GNSS receiver (SBS)	Comments
1	GNSS Observation label	"GOBS"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	Observation data	Observation file based on RINEX 3.04 format http://rtcm.info/RINEX_3.04.IGS.RTCM_Final.pdf Only data after header* is used in the context of IPIN2021-Track4.

*Header of "OBSERVATION DATA" file under Rinex 3.04 format are given later in each session specific parts (headers are slightly different).

Sample strings for OBS (observation file, based on RINEX 3.04 format) data

```
GOBS,314856.199000000,G04  24066762.037 8 126471694.10925     -3666.900          39.000
GOBS,314856.199000000,G09  21204418.682 8                9     -2579.258          24.000
GOBS,314856.199000000,G06  21843663.561 9                9     -3361.335          14.000
GOBS,314856.199000000,C24  24066200.488 4                9     -1496.777          42.000
GOBS,314856.199000000,C09  41038802.886 9 213699815.76337     -1391.943          30.000
```

```
GOBS,314856.199000000,R10  20885796.375 8 111333055.23728     -1125.414          35.000
GOBS,314856.199000000,R17  21027399.505 9 112521861.85837         1.771          31.000
GOBS,314856.199000000,G16  24420695.497 9               9      -607.284          34.000
GOBS,314856.199000000,E25  26416183.541 9               9       1623.139         22.000
GOBS,314856.199000000,R09  23641111.957 9               9      -3901.952         26.000
GOBS,314856.199000000,E24  27240945.515 8               9       -857.287         38.000
GOBS,314856.199000000,E05  27154158.133 8               9      -2871.781         35.000
GOBS,314856.399000000,G04  24066902.088 8 126472426.50726      -3656.825         35.000
GOBS,314856.399000000,G09  21204516.880 8               9      -2576.887         25.000
GOBS,314856.399000000,G06  21843791.401 9               9      -3361.335         14.000
GOBS,314856.399000000,C24  24066258.112 4 125319321.10437      -1491.643         44.000
GOBS,314856.399000000,C09  41038856.136 8 213700093.52228      -1387.629         30.000
GOBS,314856.399000000,R10  20885839.907 8 111333279.85427      -1119.290         37.000

…

GOBS,316465.400000000,G09  22053796.355 9               7      -2965.625         42.000    22053774.011 9
9     -2311.088          23.000
GOBS,316465.400000000,G06  22958748.483 8               9      -3890.580         43.000    22958742.892 9
9     -3018.360          18.000
GOBS,316465.400000000,G04  25190987.721 9               9      -3672.705         35.000
GOBS,316465.400000000,G20  20618874.632 4               9       1326.448         48.000
GOBS,316465.400000000,G07  20956968.745 8               9       -528.696         32.000
GOBS,316465.400000000,C14  26537412.626 9               9      -3269.531         39.000
```

Column	ground truth position	Comments
1	ground truth position label	"POSI"
2	GPS Time of Week (ToW) in second	GPS Time of Week (ToW) in second
3	WGS84 longitude in decimal degrees	
4	WGS84 latitude in decimal	
5	Floor Number in integer	0 : Ground Floor, -1, 1, 2
6	POSI number index	

Sample strings for ground truth position data

```
POSI,308945.294,-1.6313191524195993,47.22617430160391,-1,1
POSI,308960.836,-1.6310604539849840,47.22612380681056,-1,2
```

Note1: POSI frame is only used twice in scoring trials. For the first Key Point (n°1) and the second Key Point (n°2).
Note2: POSI frame is used in testing trial to help competitors to tune their algorithm.

Testing Trial#1: dataset recorded around 15h45 (local time), the 15th of September 2021 in Nantes

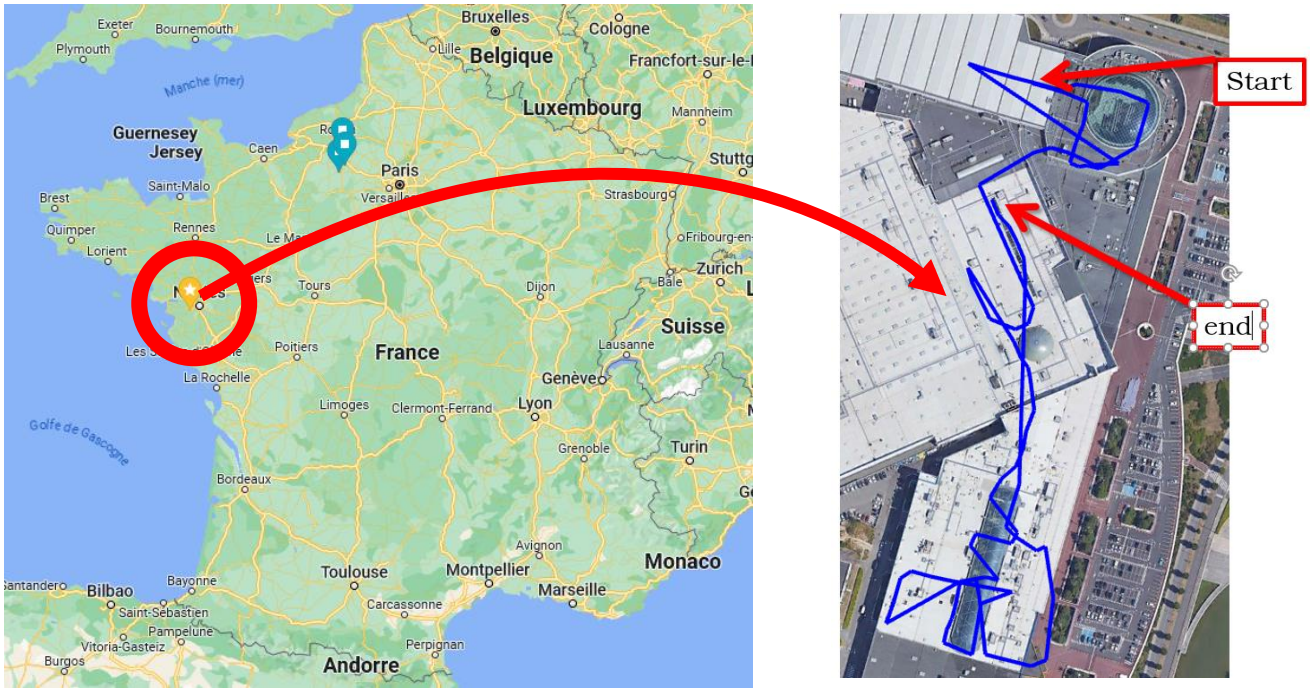
The materials and methods provided by the competition organizers are:

Type	Description	URL to download
Testing Trial#1	CSV file containing all data as described in section "Description of Datasets". GroundTruth is given inside IPIN2022_T4_TestingTrial01.txt under POSI frames.	https://evaal.aaloa.org/files/2022/IPIN2022_T4_Trials.7z
Allan Variance	static logfile of more than 15 hours that can be used for sensors bias estimation.	http://evaal.aaloa.org/images/2021/track4/2021.09_ULISS_AllanVariance.zip
Magnetometer Calibration	logfile of about 1 minute that can be used to calibrate the magnetometer sensor	http://evaal.aaloa.org/images/2021/track4/2021.09.15_ULISS_MagCalib.zip
GNSS Navigation file	contains ephemeris data for those who want to use GNSS sensor. (format RINEX 3.04)	http://evaal.aaloa.org/images/2021/track4/session1_gnss.nav
GNSS Observation header	3.04 OBSERVATION DATA M: Mixed RINEX VERSION / TYPE RTKCONV demo5 b34c 20210930 154220 UTC PGM / RUN BY / DATE format: u-blox UBX COMMENT log: D:\IPIN2021\DataCollection\2021.09.15_15h30_Acqui1\ULISCOMMENT MARKER NAME MARKER NUMBER MARKER TYPE OBSERVER / AGENCY REC # / TYPE / VERS ANT # / TYPE 4337853.3676 -123576.7925 4658733.9793 APPROX POSITION XYZ 0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N G 8 C1C L1C D1C S1C C2X L2X D2X S2X SYS / # / OBS TYPES R 8 C1C L1C D1C S1C C2C L2C D2C S2C SYS / # / OBS TYPES E 8 C1X L1X D1X S1X C7X L7X D7X S7X SYS / # / OBS TYPES S 4 C1C L1C D1C S1C SYS / # / OBS TYPES C 8 C2I L2I D2I S2I C7I L7I D7I S7I SYS / # / OBS TYPES 2021 09 15 13 48 01.2070000 GPS TIME OF FIRST OBS 2021 09 15 14 33 04.2070000 GPS TIME OF LAST OBS G L1C SYS / PHASE SHIFT G L2X -0.25000 SYS / PHASE SHIFT R L1C SYS / PHASE SHIFT R L2C SYS / PHASE SHIFT E L1X 0.00000 SYS / PHASE SHIFT E L7X 0.00000 SYS / PHASE SHIFT S L1C SYS / PHASE SHIFT C L2I SYS / PHASE SHIFT C L7I SYS / PHASE SHIFT 12 R01 1 R02 -4 R07 5 R08 6 R09 -2 R10 -7 R11 0 R16 -1 GLONASS SLOT / FRQ # R17 4 R22 -3 R23 3 R24 2 GLONASS SLOT / FRQ # C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000 GLONASS COD/PHS/BIS END OF HEADER	
RINEX 3.04 spec	Specification of RINEX format The Receiver Independent Exchange Format, Version 3.04	http://evaal.aaloa.org/images/2021/track4/RINEX_3.04.IGS.RTCM_Final.pdf

- **Key Points:**
  - **84 key points re listed in this Testing Trial, under POSI lines in both IPIN2022_T4_TestingTrial01.txt, and EvaalAPI datastream.**

- Evaluation is based like other Tracks: i.e. position has to be computed and sent twice a second (~2Hz), synchronized with the evaal data stream, and thus corresponding to the end of each dataset window of 0.5s.
- The output format is described in the chapter "Description of the Output File" here after.

- **Points given in order to get a good first heading:**
  - **Coordinates of Key Point n°1:**
    - **GPS Time of Week in seconds:** *308945.294*
    - **WGS84 longitude in decimal degrees:** *-1.631319152*
    - **WGS84 latitude in decimal degrees:** *47.226174301*
    - **Floor Number in integer:** *-1*
  - **Coordinates of Key Point n°2:**
    - **GPS Time of Week in seconds:** *308960.836*
    - **WGS84 longitude in decimal degrees:** *-1.631060453*
    - **WGS84 latitude in decimal degrees:** *47.226123806*
    - **Floor Number in integer:** *-1*
- **Bird view:**

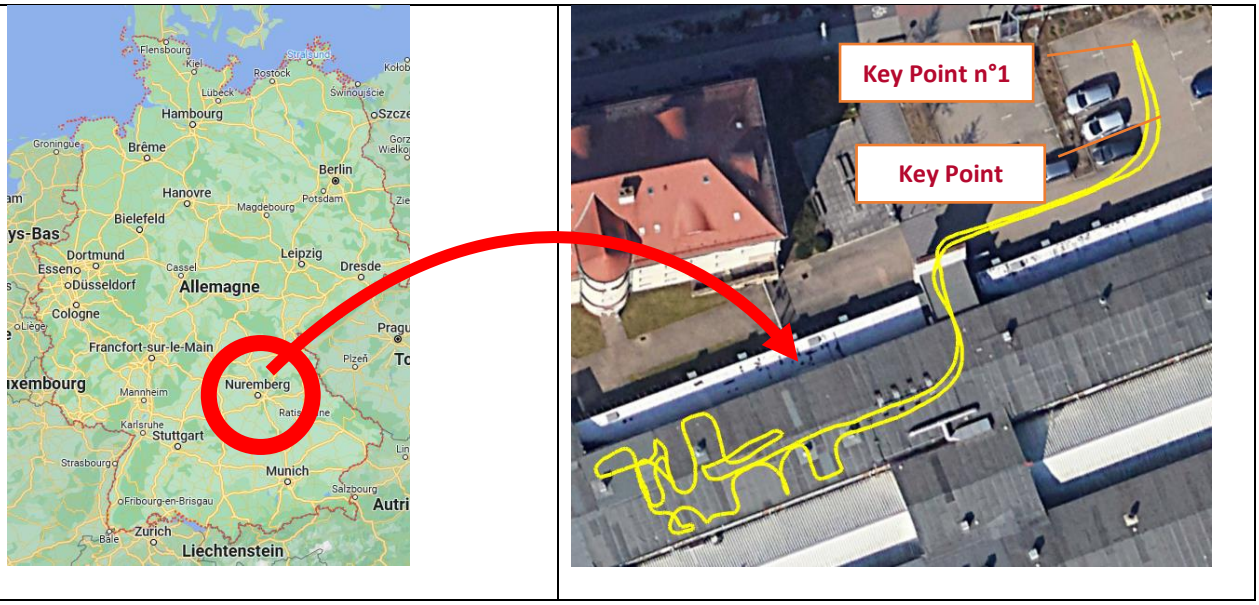


Testing Trial#2: dataset recorded around 11h30 (local time), the 14th of June 2023 in Nuremberg

Type	Description	URL to download
Testing Trial#2	CSV file containing all data as described in section "Description of Datasets". GroundTruth is given inside IPIN2023_T4_TestingTrial02.txt under POSI frames.	https://evaal.aaloa.org/files/2023/IPIN2023_T4_TestingTrial02.txt.xz
Allan Variance	static logfile of about 12 hours that can be used for sensors bias estimation.	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_AllanVariance.7z
Magnetometer Calibration	logfile of about 1 minute that can be used to calibrate the magnetometer sensor	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_MagCalib.7z
GNSS Navigation file	contains ephemeris data for those who want to use GNSS sensor. (format RINEX 3.04)	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_Trial_gnss_ephem.nav
GNSS Observation header	3.04 OBSERVATION DATA M: Mixed RINEX VERSION / TYPE RTKCONV demo5 b34c 20230713 083128 UTC PGM / RUN BY / DATE format: NovAtel OEM7 COMMENT log: D:\IPIN2023\PROPACK\Rover\NMND21380003K_2023-06-14_09-4COMMENT MARKER NAME MARKER NUMBER MARKER TYPE OBSERVER / AGENCY REC # / TYPE / VERS ANT # / TYPE 0.0000 0.0000 0.0000 APPROX POSITION XYZ 0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N G 12 C1C L1C D1C S1C C2W L2W D2W S2W C5Q L5Q D5Q S5Q SYS / # / OBS TYPES R 8 C1C L1C D1C S1C C2P L2P D2P S2P SYS / # / OBS TYPES E 8 C1C L1C D1C S1C C7Q L7Q D7Q S7Q SYS / # / OBS TYPES C 16 C2I L2I D2I S2I C7I L7I D7I S7I C7D L7D D7D S7D C5P SYS / # / OBS TYPES L5P D5P S5P SYS / # / OBS TYPES 2023 06 14 09 35 11.2000000 GPS TIME OF FIRST OBS 2023 06 14 09 45 25.4000000 GPS TIME OF LAST OBS G L1C SYS / PHASE SHIFT G L2W 0.00000 SYS / PHASE SHIFT G L5Q -0.25000 SYS / PHASE SHIFT R L1C SYS / PHASE SHIFT R L2P 0.25000 SYS / PHASE SHIFT E L1C 0.50000 SYS / PHASE SHIFT E L7Q -0.25000 SYS / PHASE SHIFT C L2I SYS / PHASE SHIFT C L7I SYS / PHASE SHIFT C L7D SYS / PHASE SHIFT C L5P 0.25000 SYS / PHASE SHIFT 1 R09 -2 GLONASS SLOT / FRQ # C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000 GLONASS COD/PHS/BIS END OF HEADER	
RINEX 3.04 spec	Specification of RINEX format The Receiver Independent Exchange Format, Version 3.04	http://evaal.aaloa.org/images/2021/track4/RINEX_3.04.IGS.RTCM_Final.pdf

- Note about Maps use
  - Even if maps may be allowed in others tracks, for this one, it is NOT. Track chairs, in such a case, could cancel contributions of competitor.
  - Algorithms are not supposed to embed or access maps to enhance positioning.

- **Key Points:**
  - **30 key points re listed in this Testing Trial, under POSI lines in both IPIN2023_T4_TestingTrial02.txt, and EvaalAPI datastream.**
  - **Evaluation is based like other Tracks: i.e. position has to be computed and sent twice a second (~2Hz), synchronized with the evaal data stream, and thus corresponding to the end of each dataset window of 0.5s.**
  - **The output format is described in the chapter "Description of the Output File" here after.**
- **Points given in order to get a good first heading:**
  - **Coordinates of Key Point n°1:**
    - **GPS Time of Week in seconds:** ***293919.833***
    - **WGS84 longitude in decimal degrees:** ***11.111207986***
    - **WGS84 latitude in decimal degrees:** ***49.461512004***
    - **Floor Number in integer:** ***0***
  - **Coordinates of Key Point n°2:**
    - **GPS Time of Week in seconds:** ***293973.817***
    - **WGS84 longitude in decimal degrees:** ***11.111139902***
    - **WGS84 latitude in decimal degrees:** ***49.461529297***
    - **Floor Number in integer:** ***0***
- **Bird view:**



Scoring Trial#1: dataset recorded around 12h20 (local time), the 14th of June 2023 in Nuremberg

Type	Description	URL to download
Testing Trial#2	SCORING TRIAL is only accessible via EvaalAPI	-
Allan Variance	static logfile of about 12 hours that can be used for sensors bias estimation.	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_AllanVariance.7z
Magnetometer Calibration	logfile of about 1 minute that can be used to calibrate the magnetometer sensor	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_MagCalib.7z
GNSS Navigation file	contains ephemeris data for those who want to use GNSS sensor. (format RINEX 3.04)	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_Scoring1_gnss_ephem.nav
GNSS Observation header	3.04 OBSERVATION DATA M: Mixed RINEX VERSION / TYPE RTKCONV demo5 b34c 20230712 153016 UTC PGM / RUN BY / DATE format: u-blox UBX COMMENT log: D:\IPIN2023\ULISS1\Scoring#1\uliss-1-trace-703\gnss.ubxCOMMENT MARKER NAME MARKER NUMBER MARKER TYPE OBSERVER / AGENCY REC # / TYPE / VERS ANT # / TYPE 4075956.6082 800546.3329 4824370.6667 APPROX POSITION XYZ 0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N G 8 C1C L1C D1C S1C C2X L2X D2X S2X SYS / # / OBS TYPES R 8 C1C L1C D1C S1C C2C L2C D2C S2C SYS / # / OBS TYPES E 8 C1X L1X D1X S1X C7X L7X D7X S7X SYS / # / OBS TYPES S 4 C1C L1C D1C S1C SYS / # / OBS TYPES C 8 C2I L2I D2I S2I C7I L7I D7I S7I SYS / # / OBS TYPES 2023 06 14 10 07 37.0020000 GPS TIME OF FIRST OBS 2023 06 14 10 39 30.6020000 GPS TIME OF LAST OBS G L1C SYS / PHASE SHIFT G L2X -0.25000 SYS / PHASE SHIFT R L1C SYS / PHASE SHIFT R L2C SYS / PHASE SHIFT E L1X 0.00000 SYS / PHASE SHIFT E L7X 0.00000 SYS / PHASE SHIFT S L1C SYS / PHASE SHIFT C L2I SYS / PHASE SHIFT C L7I SYS / PHASE SHIFT 10 R01 1 R02 -4 R03 5 R09 -2 R10 -7 R15 0 R16 -1 R17 4 GLONASS SLOT / FRQ # R18 -3 R19 3 GLONASS SLOT / FRQ # C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000 GLONASS COD/PHS/BIS END OF HEADER	
RINEX 3.04 spec	Specification of RINEX format The Receiver Independent Exchange Format, Version 3.04	http://evaal.aaloa.org/images/2021/track4/RINEX_3.04.IGS.RTCM_Final.pdf

- **Note about Maps use**
  - Even if maps may be allowed in others tracks, for this one, **it is NOT**. Track chairs, in such a case, could cancel contributions of competitor.
  - Algorithms are not supposed to embed or access maps to enhance positioning.
- **Key Points**:
  - We target between 80 and 100 key points for evaluation of Track4

- Evaluation is now based like other Tracks: i.e. position has to be computed and sent twice a second (~2Hz), synchronized with the evaal data stream, and thus corresponding to the end of each dataset window of 0.5s.

- The output format is described in the chapter “Description of the Output File” here after.

- **Points given in order to get a good first heading:**

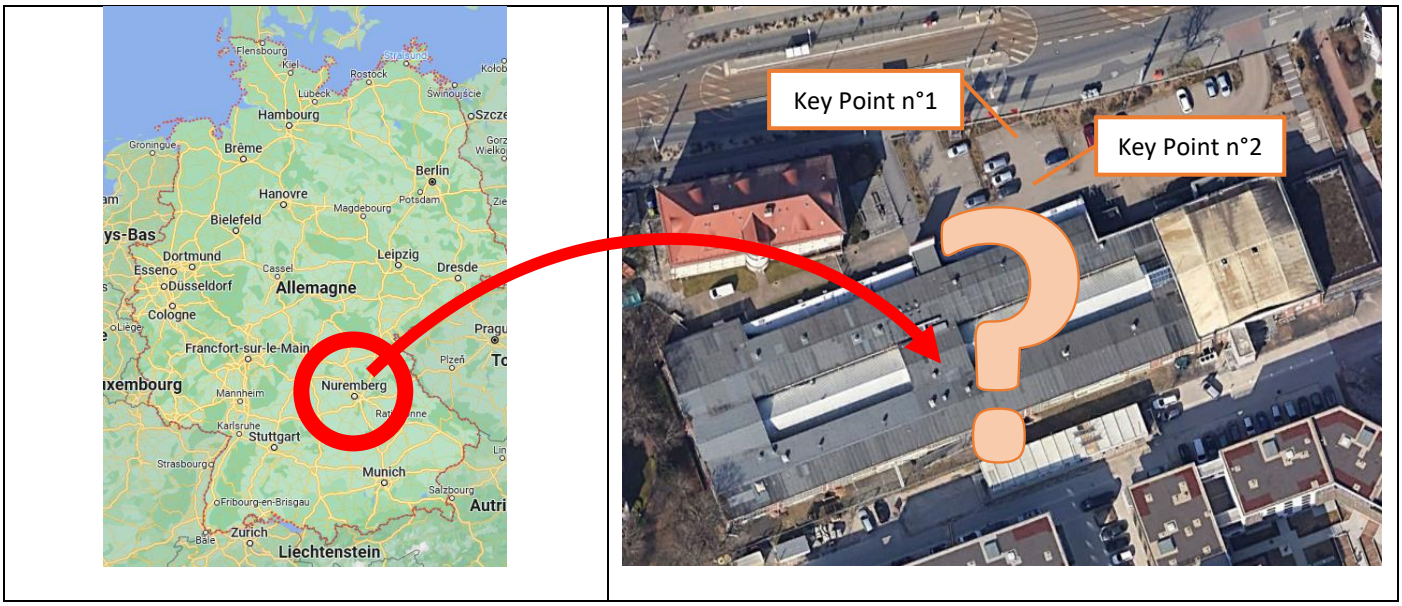
  - **Coordinates of Key Point n°1:**

    - **GPS Time of Week in seconds:** ***coming soon***
    - **WGS84 longitude in decimal degrees:** ***coming soon***
    - **WGS84 latitude in decimal degrees:** ***coming soon***
    - **Floor Number in integer:** ***0***
    - **Corresponding POSI line:** ***coming soon***

  - **Coordinates of Key Point n°2:**

    - **GPS Time of Week in seconds:** ***coming soon***
    - **WGS84 longitude in decimal degrees:** ***coming soon***
    - **WGS84 latitude in decimal degrees:** ***coming soon***
    - **Floor Number in integer:** ***0***
    - **Corresponding POSI line:** ***coming soon***

- **Bird view:**



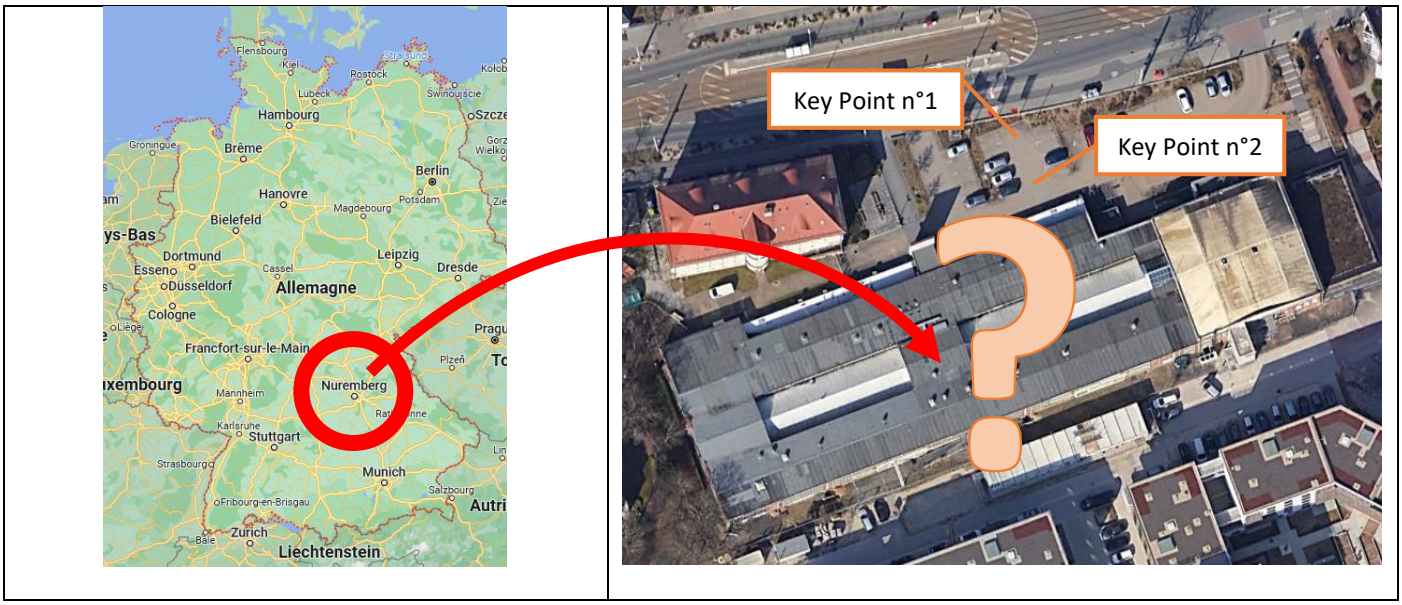
Scoring Trial#2: dataset recorded around 15h00 (local time), the 14th of June 2023 in Nuremberg

Type	Description	URL to download
Testing Trial#2	SCORING TRIAL is only accessible via EvaalAPI	-
Allan Variance	static logfile of about 12 hours that can be used for sensors bias estimation.	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_AllanVariance.7z
Magnetometer Calibration	logfile of about 1 minute that can be used to calibrate the magnetometer sensor	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_ULISS_MagCalib.7z
GNSS Navigation file	contains ephemeris data for those who want to use GNSS sensor. (format RINEX 3.04)	https://evaal.aaloa.org/files/2023/IPIN2023_T4_calibration/IPIN2023_T4_Scoring2_gnss_ephem.nav
GNSS Observation header	3.04 OBSERVATION DATA M: Mixed RINEX VERSION / TYPE RTKCONV demo5 b34c 20230712 153520 UTC PGM / RUN BY / DATE format: u-blox UBX COMMENT log: D:\IPIN2023\ULISS1\Scoring#2\uliss-1-trace-704\gnss.ubx COMMENT MARKER NAME MARKER NUMBER MARKER TYPE OBSERVER / AGENCY REC # / TYPE / VERS ANT # / TYPE 4075909.0302 800518.7829 4824318.5177 APPROX POSITION XYZ 0.0000 0.0000 0.0000 ANTENNA: DELTA H/E/N G 8 C1C L1C D1C S1C C2X L2X D2X S2X SYS / # / OBS TYPES R 8 C1C L1C D1C S1C C2C L2C D2C S2C SYS / # / OBS TYPES E 8 C1X L1X D1X S1X C7X L7X D7X S7X SYS / # / OBS TYPES S 4 C1C L1C D1C S1C SYS / # / OBS TYPES C 8 C2I L2I D2I S2I C7I L7I D7I S7I SYS / # / OBS TYPES 2023 06 14 12 40 37.4010000 GPS TIME OF FIRST OBS 2023 06 14 13 13 35.0010000 GPS TIME OF LAST OBS G L1C SYS / PHASE SHIFT G L2X -0.25000 SYS / PHASE SHIFT R L1C SYS / PHASE SHIFT R L2C SYS / PHASE SHIFT E L1X 0.00000 SYS / PHASE SHIFT E L7X 0.00000 SYS / PHASE SHIFT S L1C SYS / PHASE SHIFT C L2I SYS / PHASE SHIFT C L7I SYS / PHASE SHIFT 10 R02 -4 R03 5 R04 6 R05 1 R09 -2 R10 -7 R11 0 R18 -3 GLONASS SLOT / FRQ # R19 3 R20 2 GLONASS SLOT / FRQ # C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000 GLONASS COD/PHS/BIS END OF HEADER	
RINEX 3.04 spec	Specification of RINEX format The Receiver Independent Exchange Format, Version 3.04	http://evaal.aaloa.org/images/2021/track4/RINEX_3.04.IGS.RTCM_Final.pdf

- **Note about Maps use**
  - Even if maps may be allowed in others tracks, for this one, **it is NOT**. Track chairs, in such a case, could cancel contributions of competitor.
  - Algorithms are not supposed to embed or access maps to enhance positioning.
- **Key Points**:

- We target between 80 and 100 key points for evaluation of Track4
- Evaluation is now based like other Tracks: i.e. position has to be computed and sent twice a second (~2Hz), synchronized with the evaal data stream, and thus corresponding to the end of each dataset window of 0.5s.
- The output format is described in the chapter "Description of the Output File" here after.

- **Points given in order to get a good first heading:**
  - **Coordinates of Key Point n°1:**
    - **GPS Time of Week in seconds:** ***coming soon***
    - **WGS84 longitude in decimal degrees:** ***coming soon***
    - **WGS84 latitude in decimal degrees:** ***coming soon***
    - **Floor Number in integer:** ***0***
    - **Corresponding POSI line:** ***coming soon***
  - **Coordinates of Key Point n°2:**
    - **GPS Time of Week in seconds:** ***coming soon***
    - **WGS84 longitude in decimal degrees:** ***coming soon***
    - **WGS84 latitude in decimal degrees:** ***coming soon***
    - **Floor Number in integer:** ***0***
    - **Corresponding POSI line:** ***coming soon***
- **Bird view:**



Description of the Output stream to return by competitor

For each scoring trial, competitor is asked to give processed data inside the field "position" of the *GET /TRIAL/nextdata* EvaalAPI request. The string "position" has to be composed of the 4 following fields:

- Field 1: WGS84 longitude in decimal degrees with at least 9 decimal digit resolution
- Field 2: WGS84 latitude in decimal degrees with at least 9 decimal digit resolution
- Field 3: Floor Number in integer (0 : Ground Floor, -1, 1, 2)
- Field 4: Incrementing counter starting from 1. 1 being the first point computed by competitor, 2 being the second, and so on…

Comma (",") has to be used as data delimiter.

Assessment will take into account the PTS (timestamp relative to the last position) return by *GET /TRIAL/estimates* EvaalAPI request.

Examples of successive string "position" included in *GET/TRIAL/nextdata* requests:

```
-1.542614572,47.217689856,0,1
-1.542614573,47.217689855,0,2
-1.542614574,47.217689854,2,3
…
```

Corresponding example of *GET/TRIAL/estimates* request:

```
pts,c,h,s,pos
217034.000,0.000,0.000,45.000,-1.542614572,47.217689856,0,1
217034.500,1662121746.081,0.500,43.762,-1.542614572,47.217689856,0,1
217035.000,1662121747.877,0.500,45.000,-1.542614573,47.217689855,0,2
217035.500,1662121749.670,0.500,45.000,-1.542614574,47.217689854,2,3
…
```

Evaluation criterion

The final metric will be based on the accuracy for the correct floor detection and the horizontal positioning error. In particular, the score for comparing the different location systems will be based on the following equations:

$$\textbf{Accuracy Score} = \text{3rdQuartile}\{\text{SampleError}(R_i, E_i)\}, \forall \text{ groundtruth reference in all final test sets}$$

$$\text{SampleError}(R_i, E_i) = \text{Distance}(R_i, E_i) + (\text{penalty} \times \text{floorfail})$$

where:

- "3rdQuartile" is the third quartile error, in meters, of a cumulative error distribution function, i.e., the error value that includes 75% of estimations (sample errors) with a lower error.
- R_i is the actual position (ground truth).
- E_i is the predicted position by the method proposed by the contest participant.
- floorfail is the absolute difference between actual floor and the predicted one.
- penalty is used to penalize errors in estimating the floor. penalty is set to 15 m.
- $\text{Distance}(R_i, E_i)$ calculates the Euclidean distance between coordinates (longitude and latitude) of R_i and E_i.

The team with the lower "Accuracy Score" wins.

Contact points and information

For any further question about the database and this competition track, please contact to:

- Miguel Ortiz (miguel.ortiz@univ-eiffel.fr) at the University Gustave Eiffel, France.
- Ni Zhu (ni.zhu@univ-eiffel.fr) at the University Gustave Eiffel, France.

Introduced changes

For any further question about the database and this competition track, please contact to:

Version 1.0	April 21st	First version
Version 2.0	**July 13th**	**-Add of a second TrialTesting recorded on Nuremberg site -Add of 2 initialization Key Point and Bird view on TestingTrial#1**